

AVANGO

Programming introduction



AVANGO

- **av-sh and aview:** the basic shells
- Scheme scripting
- Scheme bindings
- **Tasks**
 - Shell execution 1
 - Shell execution 2
 - Manipulating scene graph geometry
 - Simple data routing
 - Creating new nodes: subclassing AVANGO nodes



The AVANGO shells

- Two shells available:
 - av-sh, run `$AV_HOME/bin/av-sh.sh`
 - aview, run `$AV_HOME/bin/aview.sh`
- Both shells run the same binary
- Shells run a scheme interpreter with AVANGO objects available
- Behavior and appearance is changed via command line options



The AVANGO shells

- Supported architectures:
 - irix: N32_mips3, N32_mips4, 64_mips3, 64_mips4
 - linux: IA32_I586, IA32_I686



The AVANGO shells

■ Basic command line options

- A <arch> : use binaries and libraries for <arch> or
- D <arch> : use debuggable binaries and libraries for <arch>
- d <string> : use <string> as command to execute av-sh.sh with
- t : turn on tracing
- v : turn on verbose operation
- x : disable screensaver during program execution
- z : enable OpenGL|Performer debug library search paths
- h|-? : help screen



The AVANGO shells

■ Basic command line options

- av-sh [-a <arena-size (mb)>]
- [-H <elk-heap-size (mb)>]
- [-m <multi-processing-mode>]
- [-n <notify-level>]
- [[-p <pipe-display>] ...]
- [-P <preload-type>]
- [-L <preload-file>]
- [-f <scheme-file>]
- [-o <option>:<value>] [-h]



The AVANGO shells

- Basic command line options
 - All parameter passed to `aview.sh` will be passed to `av.sh`
 - `aview` is just an `av-sh` with some preloaded configuration options and scheme scripts that set up the basic viewing window



The AVANGO shells

- `aview`
 - **Avview can be used to view Avocado scenes on any output device thinkable. It is highly configurable and supports the Cave, theWorkbench and screen output for now**
 - **It sets up the a suitable viewer for the selected output device andenables all known interaction devices**



AVANGO task 1: shell execution

- Run both shells by executing

- av-sh.sh
 - aview.sh

“Examine the nice difference”

- Run the aview with an arbitrary geometry file by just typing

- aview.sh <your desired file>



AVANGO task 2: shell execution

- aview has by default a somehow strange moving model
- The –o options: All –o <option:value> pairs are accessible from your scheme code
- Change your aview configuration by running aview with the option

- o device:mon



The AVANGO shells

- There is one basic shell binary
- The shell implements a basic scheme interpreter
- All configuration is done by
 - command line parameters
 - scheme scripts
- Aview can load arbitrary geometry



AVANGO scheme scripting

- Remember: The shell implements a basic scheme interpreter
- A scheme script can be loaded via the `-f <scriptfile>` option
- There is an approach to implement different scripting languages using a common scripting interface



AVANGO scheme scripting

■ Example 1

```
(define myvar 1)

(set! myvar 2)

(define mynode (make-instance-by-name „anode"))

(-> (-> mynode 'Name) 'set-value „myname")
(fp-set-value mynode 'Name „myname")

(if (fp-option-value "verbose")
    (begin
      (printf "aview: loading setup ...\\n")
    ))
```



AVANGO scheme scripting

■ Example 2 aview built-ins

(av-help)	- display this text
(av-reset)	- reset the viewer position
(av-open "filename")	- load geometry from 'filename' and replace old
(av-import "filename")	- load geometry from 'filename' and add to old
(av-load "filename")	- load scheme file with overloaded scene-root
(av-clear)	- delete scene graph
(av-dump <node>)	- dump the fields of a node and their values to stdout
(av-add <node>)	- add graph to root node



AVANGO scheme scripting

■ Example 2 cont. aview built-ins

`av-lib-vicinity` - the vicinity in which the aview support files can be found
`av-data-vicinity` - the vicinity in which the aview data files can be found
`av-view-sensor` - the main view sensor in use.
`av-main-screen` - the main screen. this is useful for calibration scripts
`av-viewer` - the viewer node. this node is referenced by the `av-view-sensor` and define the viewer position. by default it is connected via field connection to the Matrix field of a `fpFlyer`.



AVANGO scheme scripting

■ Example 2 cont. aview built-ins

`av-mover` - by default a `fpFlyer` node connected to `av-viewer`
`av-head` - if we are in a head tracked environment this is a reference to the node which represents the head. in non head tracked environments this is equal to `av-viewer`.



AVANGO scheme scripting

■ Example 2 cont. aview built-ins

`av-right-eye` - in a stereo projection environment these are references to the nodes which represent the left and right eyes of the viewer. in non stereo projection environments they are equal to `av-viewer`.

`av-stylus` - if the output device supports a stylus like device this is a reference to a `fpToolStylus` node with a `fpPointTool` connected.

`av-stick` - if an input device in form of a joystick is supported, this is referenced here.

`av-output-device` - this variable can be used to make scripts output device dependent.



AVANGO task 3: the scene graph

- Create a basic scene graph with 4 objects and two layers. Manipulate the approp. matrix fields and alter the position of the objects. Play around with different values and see the results.

```
(define node1 (make-instance-by-name „fpLoadFile“))
(define node2 (make-instance-by-name „fpGroup“))
...
(fp-set-value node1 `Filename „<my-desired>“)
(av-add node2)
(fp-add-lvalue node2 `Children node1)
(fp-set-value node1 `Matrix (make-trans-mat x y z))
...
```



AVANGO bindings

- There are scheme bindings for all necessary object types.

For example, certain always needed data types like a matrix need a scheme binding that can be manipulated from the scheme side:

```
mat?                                is it a matrix?
make-mat a00 a01...a33 create a matrix
make-trans-mat x y z create a translation matrix
mult-mat mat1...matn multiply the matrices
...

```

AVANGO task 4: simple data routing

- Create a scene with a fpTimeSensor and a fpText node. Connect the time-sensors `time` field to the text-nodes `TimeString` field. Load that scheme file in your preferred aview.

```
(define mytime (make-instance-by-name
                „fpTimeSensor“))
(define txt (make-instance-by-name „fpText“))
(fp-set-value txt 'Name „MyTextNode“)
(fp-set-value txt 'Color (make-vec4 1 0 0 1))
do some more for the txt fields Mat, Justify or DrawStyle as you wish.
```

```
...
(av-add ...) you already should know what to to here
(-> (-> txt 'TimeString) 'connect-from
     (-> mytime 'Time))
...

```

AVANGO task 5: Creating your own objects

- AVANGO is extensible.
 - If you don't find a node that suits your needs, just create a new one and make it available to the scripting layer.
 - You have to implement certain features in C++ to enable the AVANGO functionality.



AVANGO task 5: Creating your own objects

- Create a new node type that gets time input and generates a scaling matrix in a certain range. Tip: Use an fpDCS as the basic object to subclass and change its matrix with the newly calculated scaling values.

```
class fpNewClass : public fpDCS {
    FP_FC_DECLARE();
public:
    fpNynewClass();           //constructor
    virtual ~fpNewClass();    //destructor
    fpSFFloat TimeIn;         // some fields
    fpSFFloat Active;         //  "  "
    virtual void evaluate();
    virtual void evaluateLocalSideEffect();
    virtual void fieldHasChanged(fpField&);
    virtual void fieldHasChangedLocalSideEffect(fpField&);
private:
    static pfType *classType;
};
```



AVANGO task 5: Creating your own objects

```
FP_FC_DEFINE(fpNewClass)
fpType *fpNewClass::classType = 0;
fpNewClass::fpNewClass(): your init values
{
    FP_FC_START_CONSTRUCT(fpDCS);
    FP_FC_ADD_FIELD(TimeIn, 0.0);
    FP_FC_ADD_FIELD(Active, false);
    ...
    FP_FC_FINISH_CONSTRUCT();
}
fpNewClass::initClass(){
    if (classType == NULL) {
        fpDCS::initClass();
        classType = new pType(fpDCS::getClassType(),
        „fpNewClass");
        FP_FC_INIT(fpDCS, fpNewClass, TRUE, classType);
    }
}
```

AVANGO task 5: Creating your own objects

```
fpNewClass::evaluateLocalSideEffect(){
    double elapsed = TimeIn.getValue() - _lastTime;
    if ( Active.getValue()){
        // do your stuff here
    }
}
fpNewClass::fieldHasChangedLocalSideEffect(field){
    if (&field == &Active)
        // do something

    if (&field == &TimeIn)
        // do something else
    ...
}
```

AVANGO task 5: Creating your own objects

- Example c++ header file
- Example c++ source file
- Example Makefile

